## Status

of the

# **Beam Diagnostics**

and the

# **Computer Controls**

for the

## 400 MeV/805 MHz Fermilab Linac

Elliott McCrory Thursday December 12, 1991

### I. Diagnostics

- A. List of Devices; Status
- B. Arrangement/Layout

#### II. Controls

Layout/overview; Hardware; Network; Software

# **Beam Position Monitors**

One BPM in all but 2 quads; readout electronics for one plane of each BPM, but cabling for all.

Fabrication Complete hardware, electronics, readout

Calibration Results,  $R=(1.890 \pm .005) dB/mm$ Centering Algorithm Steering Algorithm

# **Resistive Wall-current Monitors**

Delta-t phase pickup, rudimentary bunch-length detector and beam toroid.

Fabrication complete on 7 of 8

#### Linac Beam Steering

Existing software utilizes 2 wire scanners and 4 dipole trim magnets (2 horizontal & 2 vertical) to center the beam as it exits the linac. In the Linac upgrade, we are concerned with actively steering the beam along the entire length of the linac.

One of the more commonly used steering algorithms involves using N Beam Position Monitors and M dipole correcting magnets with N > M.

The initial distorted orbit is described by an N-vector  $X_0$ , the displacement at each beam detector. An array of dimension M,  $\theta$  consists of the angular kicks given by the dipole magnets, so the final particle position is given by:

$$X_f = X_O + T \theta$$

We then proceed with a least squares minimization of:

$$S = (X_o + T\theta) \bullet (X_o + T\theta)$$

i.e. 
$$\frac{\partial S}{\partial \theta_k} = 0 \Rightarrow \theta = -(\tilde{T}T)^{-1} \tilde{T}X_0$$

where 
$$T_{ij} = \sqrt{\beta_i \beta_j} \sin \Delta \Phi$$
,  $\Delta \Phi = \int_i^j \frac{ds}{\beta(s)}$ 

so given  $\beta(s)$  for the lattice, the elements  $T_{ij}$  can be calculated. Then from a measured displacement  $X_0$ ,  $\theta$  can be calculated and the proper current supplied to each of the dipole magnets.

# **Wire Scanners**

Fabrication complete, but waiting on finalization of design to include *stopping foils* on some

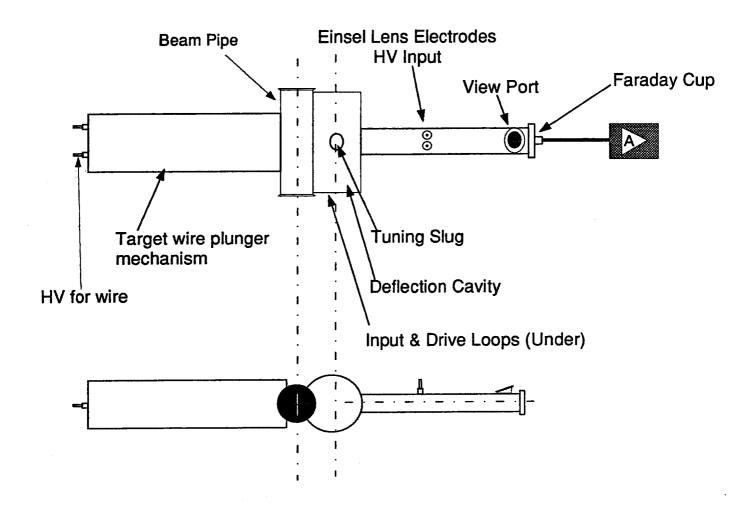
# **Bunch Length Detectors**

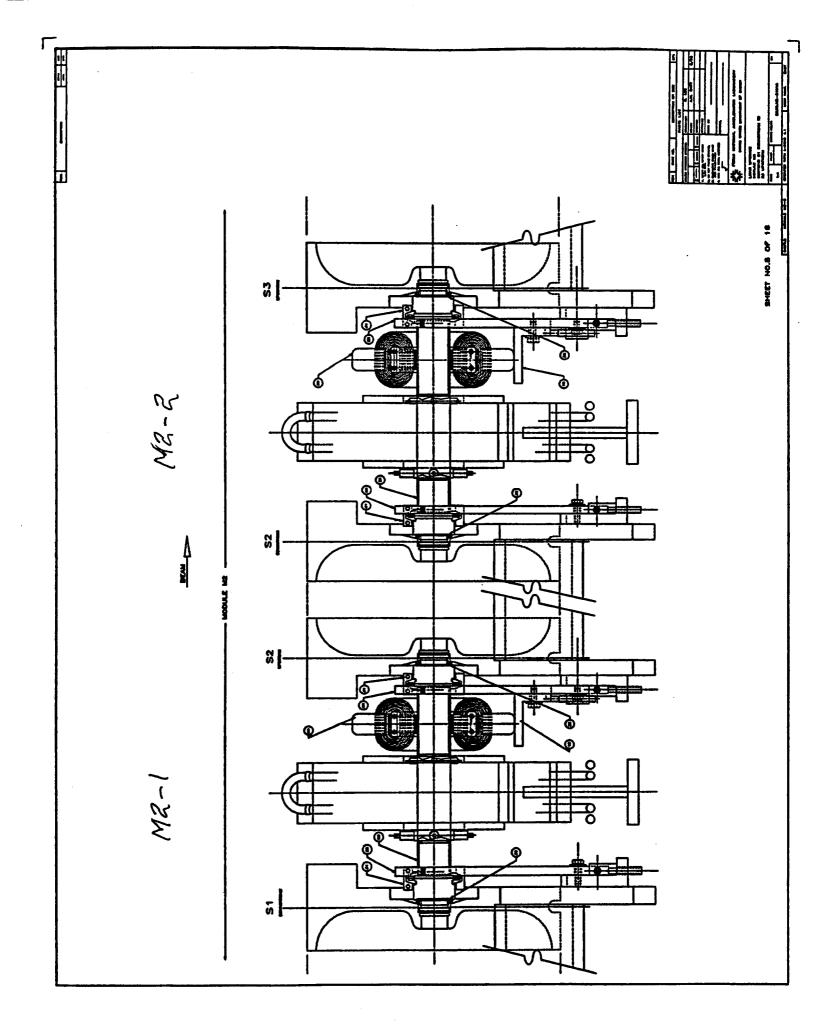
From A. V. Feschenko, with mods. Still in prototype stage. Have verified that it will work for H-minus beam; S/N≈6. Prototype deflecting cavity ready; 200 MeV prot by 3-92. Long-lead items ordered for 6 more

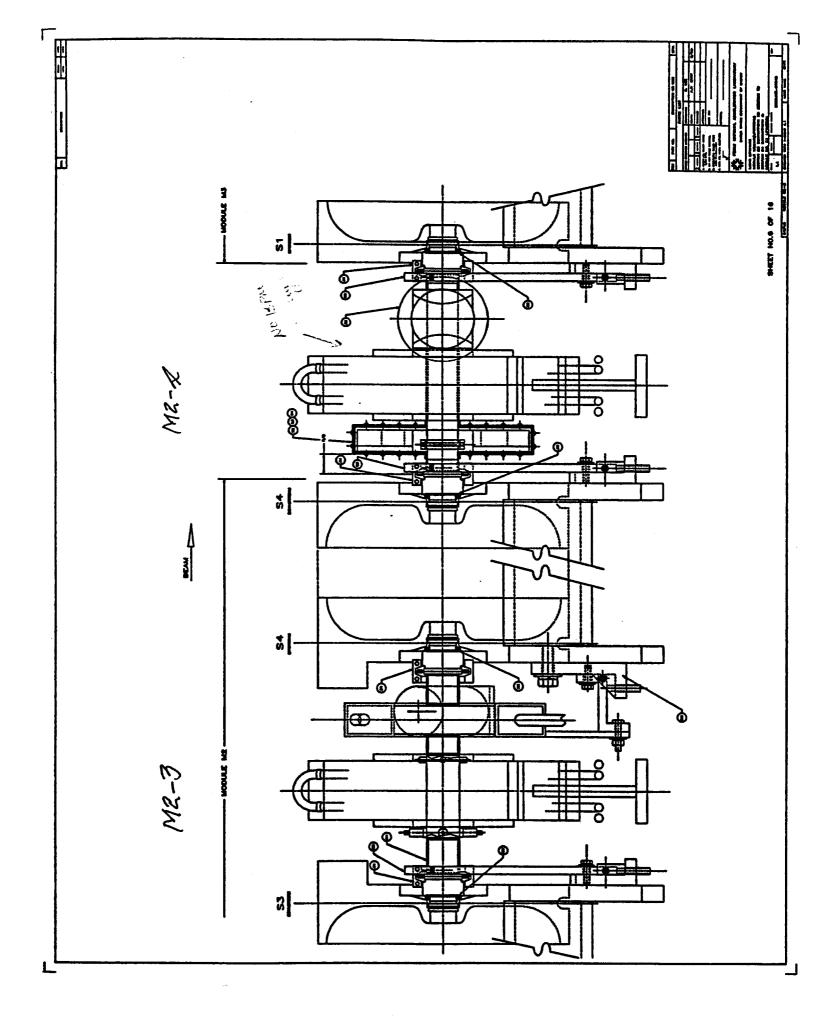
# Diagnostics Summary

All diagnostics, except BLD, are essentially done. The mechanical design of the BLD has been trickier than we originally though, but the basic design remains unchanged.

## Mechanical Schematic For 805MHz Bunch Length Detector







## List of Diagnostic Devices in 805 MHz Linac

Position	Device List		
<b>T0</b>	BPM(1), trim(1), WS, BLD		
<b>T1</b>	BPM, WS, trim(3), BLD		
T2	BPM, WS, trim(3), BLD, trim(3), BPM, RWM		
M1-1	BPM, trim(2)		
M1-2	BPM, WS		
M1-3	BPM, WS		
M1-4	RWM		
M2-1	BPM, trim(3)		
M2-2	BPM, trim(3)		
M2-3	BPM, WS		
M2-4	RWM		
M3-1	BPM, trim(3)		
M3-2	BPM, trim(3)		
M3-3	BPM, WS		
M3-4	RWM, BPM		
<b>M4-1</b>	BPM, trim(3)		
M4-2	BPM, trim(3)		
M4-3	BPM, WS		
M4-4	RWM, BPM		
M5-1	BPM, trim(4)		
M5-2	BPM, trim(4)		
M5-3	BPM, WS		
M5-4	RWM, BPM		
M6-1	BPM, trim(4)		
M6-2	BPM, trim(4)		
M6-3	BPM, WS		
<u>M6-4</u>	RWM, BPM		
M7-1	BPM, trim(4)		
M7-2	BPM, trim(4)		
M7-3	BPM, WS		
M7-4*	RWM, BPM		

#### KEY:

BPM(1) is an existing Linac BPM

trim(1) has an overall length of 3.8 cm, approx field=2600 G-cm

trim(2) has an overall length of 5.1 cm, approx field=3300 G-cm

trim(3) has an overall length of 6.4 cm, field=3990 G-cm

trim(4) has an overall length of 8.9 cm, field=5560 G-cm

\* Formerly part of the 400 MeV transfer line

# **Computer Control System**

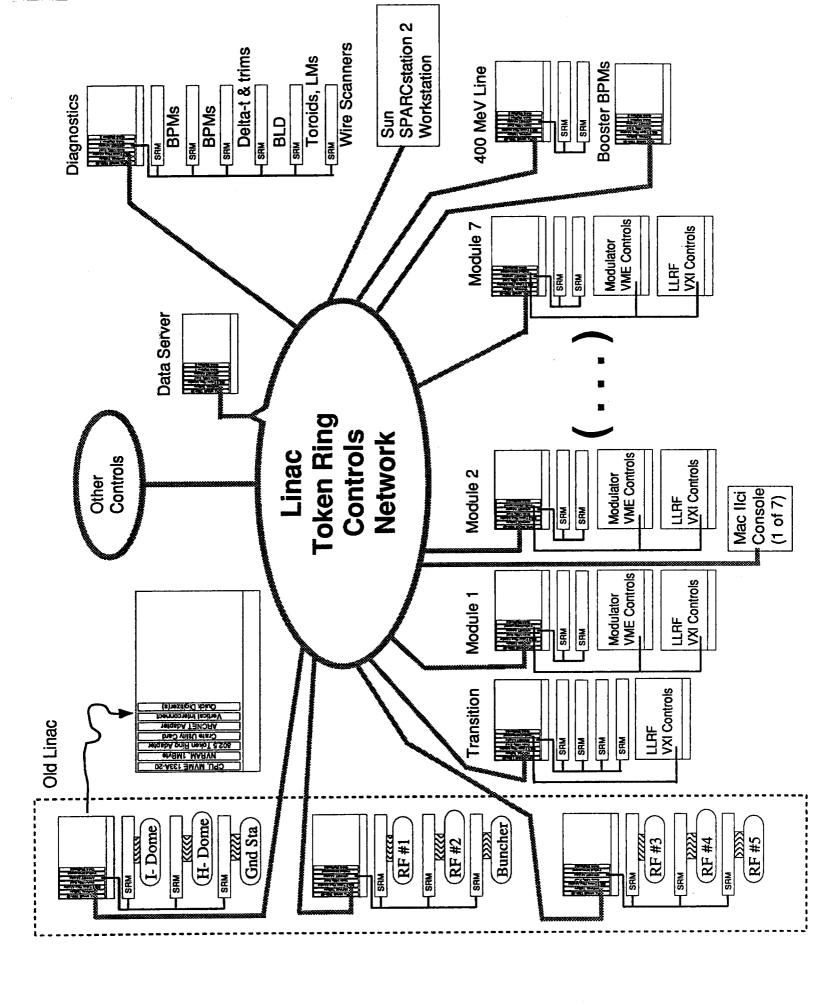
All hardware ready Upgrade of old control system begins 1-23-92.

# Layout

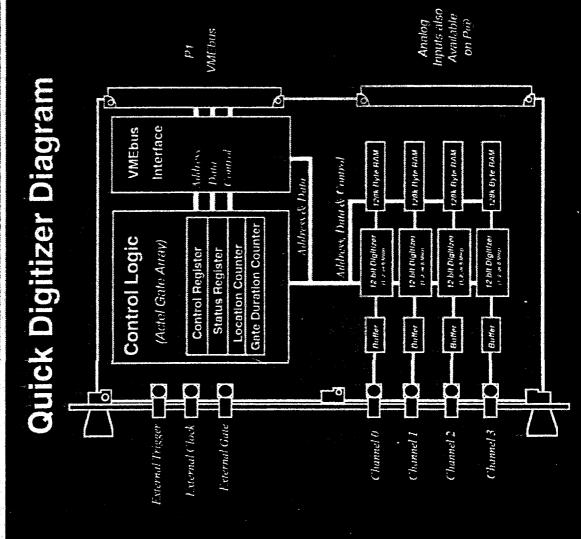
Hardware
VME, VI, SRM, Quick Digitizer

Networks
ACNET, Token Ring, ARCNET, Data Server

Application Programs
Local Applications (LA), MCR, Unix, Macintosh



# ICALEPCS 1991, Tsukuba





# **Application Programs**

## Local Applications

There have been 15 LAs written. They duplicate the closed-loop and recovery functions in the old control system, and they implement various klystron closed-loops and some of the acnet support. In addition, we have 8 page applications and 7 other new major modules in the VME control system.

## Main Control Room

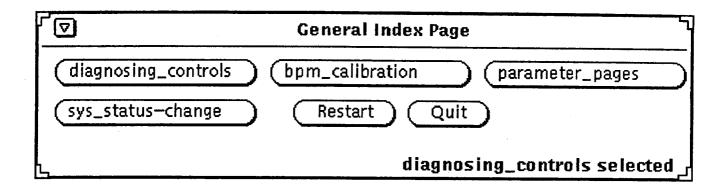
We have been able to make the improvements in the control system with only small changes in the MCR application programs.

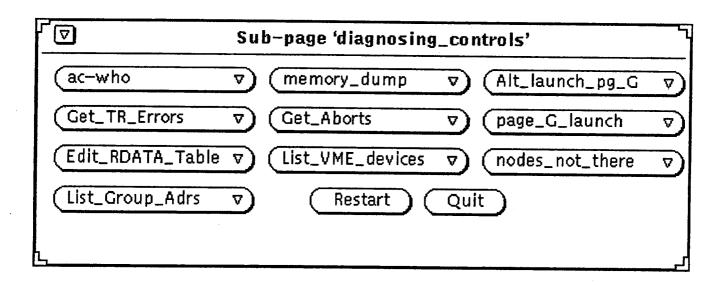
## Unix Applications

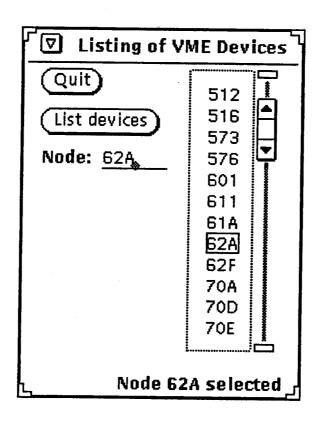
An "index page" model has been adopted and an "application program librarian" has been implemented on the Linac group's SPARCstation 2 workstation. Many simple, yet powerful programs have been written to diagnose the control system. These programs are used regularly.

## MacIntosh Applications

The parameter page and related programs on the Mac have been well-received and are being used extensively at AZero. With Mac-X, the Unix applications can run there, too.







√ ▽			get-data-base	
Quit Aga	in) (Reru	un, output to printer	Print selected text	
062A: 003A K 062A: 0080 K 062A: 0081 K 062A: 0082 K 062A: 0083 K 062A: 0085 K 062A: 0086 K 062A: 0086 K 062A: 0088 K	KAFILP KATTOP KATTOP KATC3 KATC4 KATC5 KAWGPS KAWGPS KAWG1F VAMAN KAFCI5 BADCH VASEC4 VASEC2 KAV2 KAV2 KAPHS BCHAN1 BCHAN2 KACAVV	AO FILAMENT CURR AO FILAMENT POWER TNKTEMP TOP TNKTEMP BOTTOM THERMOCOUPLE#3 THERMOCOUPLE#5 WG PRESSURE APRIL RF CH1 APRIL RF CH2 MANIFOLD KLY FOCUS #5  SECTION 4 WAVEGUIDE SECTION 2 AO VACUUM #1 AO VACUUM #1 AO VACUUM #2 RF LEAK DET 2A CAV-WG PHASE BAD CHANNEL BAD CHANNEL 2A CAV SUM VOLT 2A CAV SUM VOLT	(3.318 A ) (0.363 KW ) (98.776 F ) (95.218 F ) (33.852 DEGC) (0.006 C ) (0.008 C ) (14.639 PSIA) (-0.022 V ) (0.145 VPK) (-0.027 V ) (-1.428 V ) (-2.209 V ) (-0.255 V ) (-0.255 V ) (-0.099 V ) (-1.348 V ) (-1.348 V ) (-1.338 V ) (-1.338 V ) (-1.338 V ) (-0.004 V ) (0.005 DEG) (0.000 ) (1.459 VPK) (-0.003 VPK)	91-06-11 91-04-30 91-06-24 91-06-21 91-06-07 91-06-07 91-11-19 91-06-25 91-08-15 91-10-17 91-10-10 91-10-10 91-10-10 91-10-10 91-06-20 91-06-20 91-06-21 91-11-19 91-11-19

# **Networks**

## **ACNET**

Full ACNET support has been added to the Linac VME control stations. This includes specifically: RETDAT, SETDAT, ACNET-AUX and FTPMAN. In addition, data server support has been added for Linac-type SSDN's.

## Token Ring & ARCNET

All communications amoung systems is on the Token Ring network. Communication between a VME control station and an SRM is on ARCNET.

## Data Server

Because the MCR Vaxen and PDP11's cannot handle 15 Hz data from more than one or two Linac nodes, we have implemented a *data server* for these machines. The ACNET database entries refer to all Linac devices through this data server. We have verified that this machine can handle the potential load, with ease.